


Approximation Mechanisms: computation, representation, and incentives

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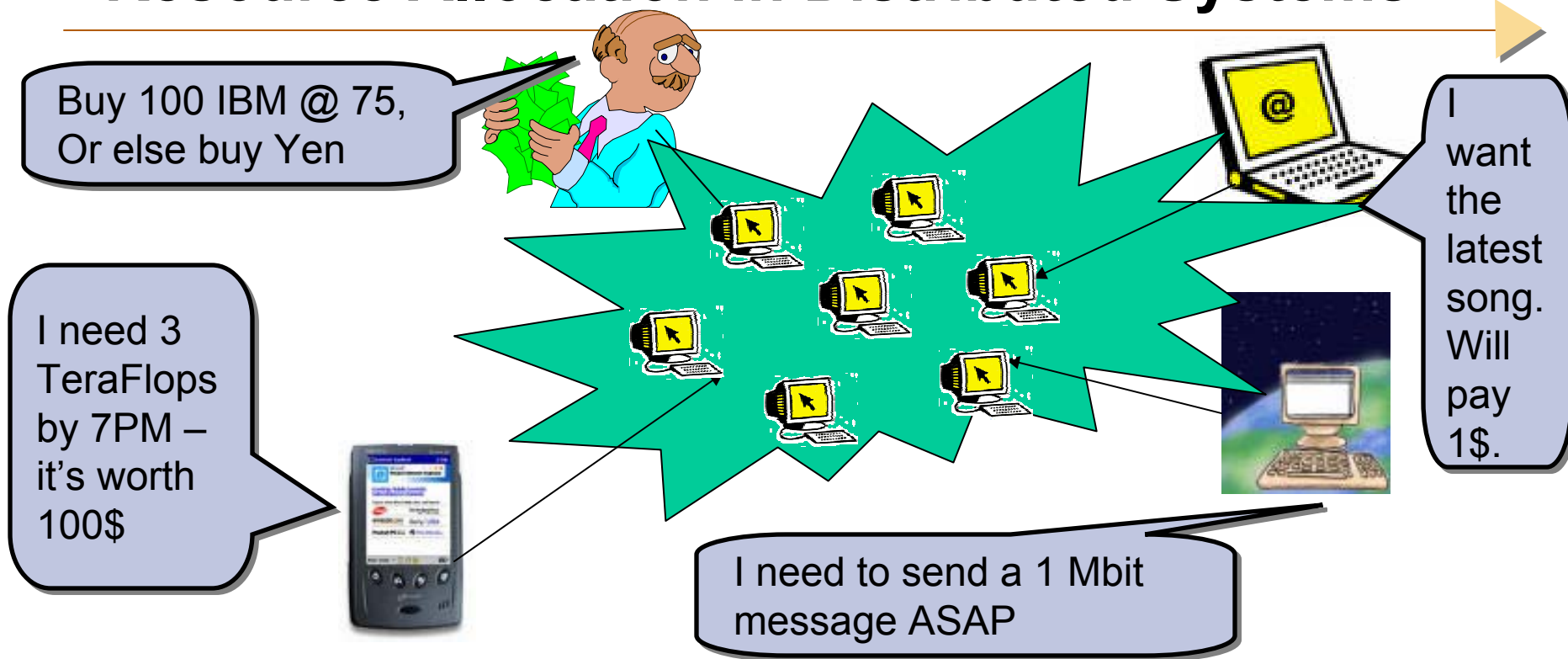
Based on joint works with Amir Ronen, Ilya Segal, Ron Lavi, Ahuva Mu'alem, and Shahrar Dobzinski

Talk Structure



- Algorithmic Mechanism Design
- Example: Multi-unit Auctions
- Representation and Computation
- VCG mechanisms
- General Incentive-Compatible Mechanisms

Resource Allocation in Distributed Systems



- Each participant in today's distributed computation network has its own *selfish* set of goals and preferences.
- We, as designers, wish to optimize some common aggregated goal.
- Assumption: participant's will act in a rationally selfish way.

Mechanisms for Maximizing Social Welfare



- Set A of possible social alternatives (allocations of all resources) affecting n players.
- Each player has a valuation function $v_i : A \rightarrow \mathcal{R}$ that specifies his *value* for each possible alternative.
- Our goal: maximize social welfare $\sum_i v_i(a)$ over all $a \in A$.
- Mechanism: Allocation Rule $a = f(v_1 \dots v_n)$ and player payments $p_i(v_1 \dots v_n) \in \mathcal{R}$.
 - Incentive Compatibility: a rational player will always report his true valuation to the mechanism.

Dominant-strategy Incentive-compatibility



For every profile of valuations, you do not gain by lying:

$$\forall i \forall v_1 \dots v_n \forall v'_i: v_i(a) - p \geq v_i(a') - p'$$

Where: $a=f(v_i v_{-i})$, $p=p_i(v_i v_{-i})$, $a'=f(v'_i v_{-i})$, $p'=p_i(v'_i v_{-i})$.

We will not consider weaker notions:

- Randomized
- Bayesian
- Approximate
- Computationally-limited
- ...

There is no loss of generality relative to any mechanism with ex-post-Nash equilibria.

The classic solution -- VCG



1. Find the welfare-maximizing alternative a
2. Make every player pay “VCG prices”:
 - Pay $\sum_{k \neq i} v_k(a)$ to each player i
 - Actually, a 2nd, non-strategic, term makes player payments ≥ 0 .
 - But we don't worry about revenue or profits in this talk.

Proof: Each player's utility is identified with the social welfare.

Problem: (1) is often computationally hard.

CS approach: approximate or use heuristics.

Problem: VCG idea doesn't extend to approximations.

Running Example: Multi-unit Auctions



- There are m identical units of some good to allocate among n players.
- $v_i(q)$ – value to player i if he gets exactly q units
- Valid allocation: $(q_1 \dots q_n)$ such that $\sum_i q_i \leq m$
- *Social welfare*: $\sum_i v_i(q_i)$

Representing the valuation



- Single-minded: (p, q) – value is p for at least q units.
- “k-minded” / “XOR-bid”: a sequence of k increasing pairs (p_j, q_j) – value is p_j , for $q_j \leq q < q_{j+1}$ units.
 - Example: “(5\$ for 3 items), (7\$ for 17 items)”
- General, “black box”: can answer queries $v_i(q)$.
 - Example: $v(q) = 3q^2$

What can be done efficiently?




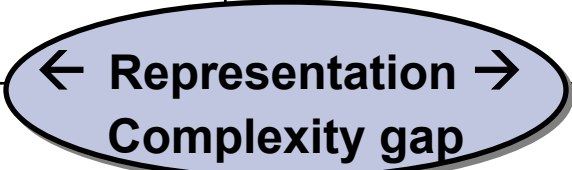
Representation → Incentives ↓	Single-minded	k-minded	general
No incentive constraints			
Incentive compatible VCG payments			
General incentive compatible			

What can be done efficiently?



Representation →	Single-minded	k-minded	general
Incentives ↓			
No incentive constraints	Computational Benchmark		
Incentive compatible VCG payments	Existing Ideas		
General incentive compatible	Our Goal		

What can be done efficiently?

Representation →	Single-minded	k-minded	general
Incentives ↓			
No incentive constraints			
Incentive compatible VCG payments			
General incentive compatible			

Approximation quality levels



- How well can a computationally-efficient (polynomial time) mechanism approximate the optimal solution?
 - **A:** Exact Optimization
 - **B:** Fully Polynomial Time Approximation Scheme (FPTAS)-- to within any $\varepsilon > 0$, with running time polynomial in $1/\varepsilon$.
 - **C:** Polynomial Time Approximation Scheme (PTAS)-- to within any fixed $\varepsilon > 0$.
 - **D:** To within some fixed constant $c > 0$ (this talk $c=2$).
 - **E:** Not to within any fixed constant.
- What we measure is the worst-case ratio between the quality (social welfare) of the optimal solution and the solution that we get.

Rest of the talk...



Representation → Incentives ↓	Single-minded	k-minded	general
No incentive constraints	B	B	B
Incentive compatible VCG payments	C	C	D
General incentive compatible	B	Conjecture: C	Conjecture + Partial result: D

Computational Status

Representation →	Single-minded	k-minded	general
Incentives ↓			
No incentive constraints	Not A NP-complete	Not A	

The SM case is exactly Knapsack:

Input: $(p_1, q_1) \dots (p_n, q_n)$

Maximize $\sum_{i \in S} p_i$ where $\sum_{i \in S} q_i \leq m$

$v_i(q) = p_i$ iff $q \geq q_i$ (0 otherwise)

Computational Status: general valuations

Representation →	Single-minded	k-minded	general
Incentives ↓			
No incentive constraints			Not A Exponential

Proof:

- Consider two players with $v_1(q)=v_2(q)=q$ except for a single value of q^* where $v_1(q^*)=q+1$.
- $v_1(q_1)+v_2(q_2)=m$ except for $q_1=q^*$; $q_2=m-q^*$.
- Finding q^* requires exponentially many (i.e. m) queries.

THM (N+Segal): Lower bound holds for all types of queries.

Proof: Reduction to Communication Complexity

Computational Status: Approximation

Representation →	Single-minded	k-minded	general
Incentives ↓			
No incentive constraints	B	B	B FPTAS

Knapsack has an FPTAS – works in general:

1. Round **prices** $v_i(q)$ down to integer multiple of δ
2. For all $k=1 \dots n$ for all $p = \delta \dots L\delta$
 - Compute $Q(k,p)$ = minimum $\sum_{i \leq k} q_i$ such that $\sum_{i \leq k} v_i(q_i) \geq p$
(Requires binary search to find minimum q_k with $v_k(q_k) \geq p'$.)

Incentives vs. approximation



Two players; Three unit $m=3$

v_1 : (1.9\$ for 1 unit), (2\$ for 2 units), (3\$ for 3 units)

v_2 : (2\$ for 1 item), (2.9\$ for 2 units), (3\$ for 3 units)

Best allocation: $1.9\$ + 2.9\$ = 4.8\$$.

Approximation algorithm with $\delta=1$ will get only $2\$ + 2\$ = 4\$$.

Manipulation by player 1: say $v_1(1 \text{ unit}) = 5\$$.

Improves social welfare \rightarrow (with VCG payments) improves player 1's utility

Where can VCG take us?



Representation →	Single-minded	k-minded	general
Incentives ↓			
No incentive constraints	B	B	B
Incentive compatible VCG payments	Not B Not better than $n/(n-1)$ approximation	Not B	Not C Not better than 2 approximation

Limitation of VCG-based mechanisms



THM (N+Ronen): A VCG-based mechanism is incentive compatible iff it *exactly* optimizes over its own range of allocations. (almost)

Proof:

- (If) exactly VCG theorem on the range
- (only if) Intuition: if players can improve outcome, they will...
- (only if) proof idea: hybrid argument (local opt \rightarrow global opt)

Corollary (N+Dobzinski): No better than 2-approximation for general valuations, or $n/(n-1)$ -approximation for SM valuations.

Proof (of corollary):

- If range is full \rightarrow exact optimization \rightarrow we saw impossibility
- If range does not include $[q_1 q_2 \dots q_n]$ then will lose factor of $n/(n-1)$ on profile $v_1=(1\$ \text{ for } q_1) \dots v_n=(1\$ \text{ for } q_n)$.

Where can VCG take us?



Representation → Incentives ↓	Single-minded	k-minded	general
No incentive constraints	B	B	B
Incentive compatible VCG payments	C	C PTAS	D 2-approximation

An incentive-compatible VCG-based mechanism

Algorithm (N+Dobzinski): bundle the items into n^2 bundles of size $t=m/n^2$ (+ a single remainder bundle).

Lemma 1: This is a 2-approximation

Proof: Re-allocate items of one bidder among others

Lemma 2: Can be computed in poly-time:

For all $k=1 \dots n$ for all $q=t \dots m/t$

Compute $P(k,q) = \text{maximum } \sum_{i \leq k} v_i(tq_i)$ such that $\sum_{i \leq k} q_i \leq q$

PTAS for k-minded case: all players except for $O(1/\epsilon)$ ones get round bundles.

General Incentive Compatibility



Representation → Incentives ↓	Single-minded	k-minded	general
No incentive constraints	B	B	B
Incentive compatible VCG payments	C	C	D
General incentive compatible			

The single-minded case



Representation → Incentives ↓	Single-minded	k-minded	general
No incentive constraints	B	B	B
Incentive compatible VCG payments	C	C	D
General incentive compatible	B FPTAS		

Single parameter Incentive-Compatibility



THM (LOS): A mechanism for the Single-minded case is incentive compatible iff it is

1. Monotone increasing in p_i and monotone decreasing in q_i
2. Payment is critical value: minimum p_i needed to win q_i

Proof (if):

- Payment does not depend on declared p ; win iff $p > \text{payment}$
- Lying with lower q is silly; higher q can only increase payment

Corollary (almost): Incentive compatible FPTAS for SM case.

The FPTAS that rounds the prices to integer multiples of δ satisfies 1&2.

Problem: Choosing δ ...

Solution: Briest, Krysta and Vöcking, STOC 2005....

What can be implemented?

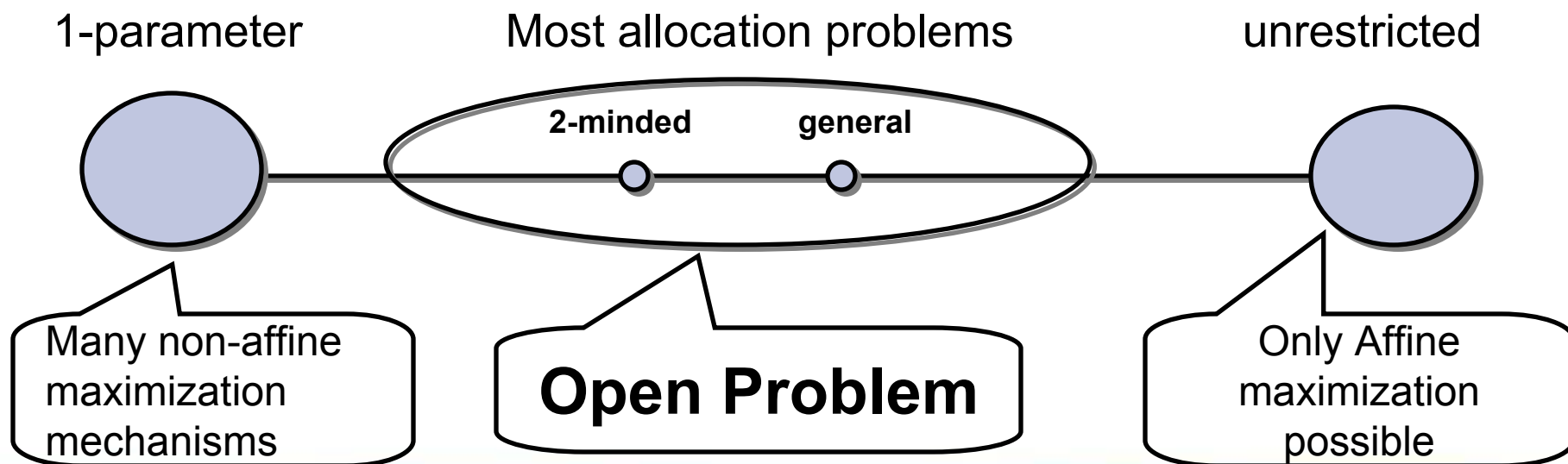


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Efficiently Computable Approximation Mechanisms?

Theorem (Roberts '77): If the space of valuations is unrestricted and $|A| \geq 3$ then the only incentive compatible mechanisms are *affine maximizers*: $\sum_i \alpha_i v_i(a) + \beta_a$

Comment: weighted versions of VCG. Easy to see that Weights cannot help computation/approximation.



Partial Lower Bound



Theorem (Lavi+Mu'alem+N): Every efficiently computable incentive compatible mechanism among two players that always allocates all units has approximation ratio ≥ 2 .

Proof idea: If range is full, must be (essentially) affine maximizer.

- Non-full range \rightarrow no better than 2-approximation
- Full range \rightarrow computationally as hard as exact social welfare maximization

Rest of talk: proof assuming full range even after a single player is fixed.

Characterization of incentive compatibility



Notation: The algorithm allocates $a=f(v, w)$ units to player 1.

Player 1 pays: $p_1(v, w)$

Characterization 1: For every w there exist payments p_a (for all a) such that for all v : $f(v, w)$ maximizes $v(a) - p_a$

Proof: $p_a(w) = p_1(v, w)$, with $f(v, w)=a$, can not depend on v .

Characterization 2 (WMON): If: $f(v, w)=a \neq b=f(v', w)$

Then: $v(a)-v(b) \geq v'(a)-v'(b)$

Proof: $v(a) - p_a \geq v(b) - p_b$

$v'(a) - p_a \leq v'(b) - p_b$

→ $v(a) - v'(a) \geq v(b) - v'(b)$

Properties of $p_a(w)$



Our Goal: for all a , $p_a(w) = \beta_a - \alpha w(m-a)$

Proof (Goal \rightarrow Theorem): By characterization 1, $f(v, w)$ maximizes $v(a) - p_a = \beta_a + v(a) + \alpha w(m-a)$

Lemma: If: $w(m-a) - w(m-b) > w'(m-a) - w'(m-b)$

Then: $p_a(w) - p_b(w) \leq p_a(w') - p_b(w')$

Proof (Lemma \rightarrow Goal): Math (next slide)

Proof (of Lemma): Otherwise choose v such that:

$$p_a(w) - p_b(w) > v(a) - v(b) > p_a(w') - p_b(w') \quad (\text{and low other } v(c))$$

By characterization 1: $f(v, w) = b$ and $f(v, w') = a$. Contradiction to WMON.

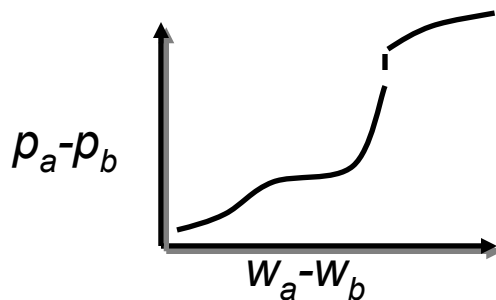
Monotonicity in differences (sketch)

Lemma: If $p : \mathcal{R}^m \rightarrow \mathcal{R}^m$ ($m \geq 3$) satisfies

$$w_a - w_b > w'_a - w'_b \Rightarrow p_a(w) - p_b(w) \geq p_a(w') - p_b(w')$$

Then for all a , $p_a(w) = \beta_a + \alpha w_a$

Proof:



$\Rightarrow p_a(w) - p_b(w)$ depends only on $w_a - w_b$ (except for countably many values.)

Claim: $\partial p_a / \partial w_a = \partial p_b / \partial w_b$ (except for measure 0 of w)

Proof: $p_a(w) - p_b(w)$ stays constant when w_a and w_b are increased by the same amount.

Corollary: $\partial p_a / \partial w_a$ is constant

Remaining Open Problem:



Are there any useful non-VCG mechanisms for CAs, MUAs, or other resource allocation problems?
(E.g. poly-time approximations or heuristics)